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The Effects of the Complementary Training on Coaching the Non-Dominant Side in Karate Shotokan

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Abstract

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Karate is a Japanese martial art, a fight with empty hands. Etymologically, *kara* means empty and *te* means hand. Karate is composed of two parts: kata (form) and kumite (fight). Both of them have individual and team competitions. Regardless of their nature, each of the competitions has techniques and basic rules according to which the referees analyse the level of the athlete and, in concordance with this, they give the point. The qualities that define the level of sports performance are: technique, strength, speed, balance, coordination. These qualities, from our point of view, should be developed at the same level on both left and right sides for improving the efficiency. This paper proposes an objective demonstration that the non-dominant side can be trained using exercises that are specific to karate, within complementary training. During this scientific work, there were achieved measurements at the muscular and neuromuscular level too, using the Electromyography (EMG), Tensiomyography (TMG) and the Conditions Simulator. The complementary training sessions were based on neuromuscular control exercises, which were performed on the left and right sides. The initial and final tests were performed on the straight punch (choku zuki) from the natural position (shizentai). The results showed an important improvement in the non-dominant side on both of the measured levels.

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Keywords: Karate; neuromuscular coordination; dominant side; conditions simulator.

1. Introduction

A Japanese martial art founded by Gikin Funakoshi, karate has become lately a sport (Funakoshi, 1998: 97). Masathoshi Nakayama and Hidetaka Nishiyama are those who established the concept of sport in karate, and the competition rules too (Nishiyama & Brown, 1992: 14).

The most important competitions are those of kata (form), individual or team, and kumite (fight), also individual and team. For each of these competitions, there are rules which help to evaluate the level of the athletes. The technical executions, rhythm, speed, distance estimation (control) are criteria



for making the difference between athletes. Since the competition level is higher and higher, coaches try to increase the efficiency of training sessions. We consider that the training of the non-dominant side of the athletes is not enough developed yet.

Lafon (1963) said that laterality means “the functional inequality of the left or right side of the body”. The inequality depends (as we will show later) on the way the two brain hemispheres are used. The left brain hemisphere controls the right side and vice versa. In this work, we intend to demonstrate that the non-dominant side of the body can be trained too. We can do that using complementary exercises, in the laboratory, in a much shorter time than in the classical training.

Laterality can be seen and revealed (Pătru et al., 2015: 6) even to the long-experienced high level athletes, and their preparation tries to diminish this deficiency, mainly in the first years of training. For the high level, we can speak about favourite combinations, but the possibility to be attacked or the opportunity to attack on the non-dominant side may occur at any moment. As there are many and diverse attack-defence possibilities, the chances of reaching a high level of performance are increasing. This is the reason why attempts are made to increase the level of neuromuscular control on the non-dominant side as near as possible to the dominant one.

The facilities offered by the conditions simulator equipment “are in connection with the athlete’s possibilities of information during each execution on the achievement of the target force centimetre by centimetre, millisecond by millisecond, with the information provided to the coach about the volume and quality throughout the training” (Hillerin, Schor, & Stupineanu, 1996). This is the reason why we have chosen this complementary type of training, pursuing the perfection of executions on the non-dominant side and a shorter time in reaching the target, too.

2. Materials and methods

The research hypothesis. During complementary training sessions, the neuromuscular control on the non-dominant side can be improved in high level athletes.

The methods used: bibliographic, observation, experiment, case study, graphical methods.

In conducting this research, we administered an initial test and a final one. The purpose was to determine the complementary training effects on the investigated subject. Testing and training were done on the wireless conditions simulator based on the CASINOR® (*Computer-Assisted Informational Orthotics*) concept. We have chosen this equipment because it gives freedom for typical karate movements (Fig. 1). The tests and training sessions were performed in the biometry laboratory of INCS (National Institute for Sport Research) in Bucharest. The researched subject was a black belt 2 DaN, 22 years old, female, a multiple national, European and World champion, with 15 years of experience, practicing kata and kumite. The athlete is right-handed.



Fig. 1. Conditions Simulator

The initial and final tests consisted in the execution of 40 chokuzuki strikes (straight punches) from the shizentai position (the natural one, where the feet are shoulder width apart). The strikes were done in series of 20 with each arm (left and right). To monitor punches, the athlete had to work on the conditions simulator with 80% break and 4 DaN power. Her task was to follow an established execution model for each execution. The athlete received real-time visual feedback on each execution. At the same time, the activity of some muscular groups was recorded with an electromyograph, using the DelsysTrigno™ Wireless System (1) equipment. Complementary training was designed to improve the efficiency of the non-dominant side and lasted 7 days. In the first 2 sessions, the subject performed 4 series of 20 consecutive strikes with the right arm and 8 with the left one. During the next 5 sessions, the series were of 10 strikes in the same working conditions (4 daN power, 80% break); the training program was customized taking into account the anthropometric particularities of the subject (52 kg weight, 167 cm height). For measuring the electric muscular activity, we used a 16-sensor electromyograph, Trigno™ Digital Wireless EMG System (Fig. 2).



Fig. 2. Trigno™ Wireless System

The Trigno sensors were fixed straight to the skin, on the belly muscle, with a special adhesive band (*Trigno™ Wireless EMG*, 2015). Taking into account the specific punch chosen for this experiment, we selected the following muscle groups: dorsal, trapeze, deltoid, finger extensors, brachial biceps, brachioradialis and finger flexors. While we monitored the quality of neuromuscular control and how the established muscle groups were functioning, the acquisitions were being done separately, on the right and left sides.

During this scientific stage, two tests were performed (the initial and final ones) on the conditions simulator. The task of the athlete was to make 20 straight punches with the right arm – choku zuki – from a natural position (shizentai), and the same thing with the left one. The purpose was to follow a graphical model with a constant force value - 4daN. The acquisition to the muscular level was achieved in the same time with the EMG. Between the two tests, a number of 7 complementary training sessions were performed using the specific move on the left and right sides. The number of repetitions on the non-dominant side was two times bigger than on the dominant one. For all the period the complementary training was done, the athlete did not interrupt her normal training. This was continued as planned.

3. Results

Figure 3 shows the initial test (left) and the final one (right) recorded on the conditions simulator for the right arm strikes (up) and the left one (down). Concerning the result of executions on the conditions simulator, in the initial test, the neuromuscular control level is lower on both sides. Even if the athlete succeeds till the end to achieve the task, she has some problems with distance estimation and her constancy in performing the strikes. In the final test, the neuromuscular control level is considerably better. The athlete can reach the task, removing the distance-estimation and constancy-related problems. In the final test, it can be seen a small variation in the executions, almost similar for both sides. In Figure 4, there are graphically represented the variations in the electric surface potentials recorded for the tested muscular groups. In Figure 5, there are specified the tested muscular groups, and the identification colours are shown in Figure 4.

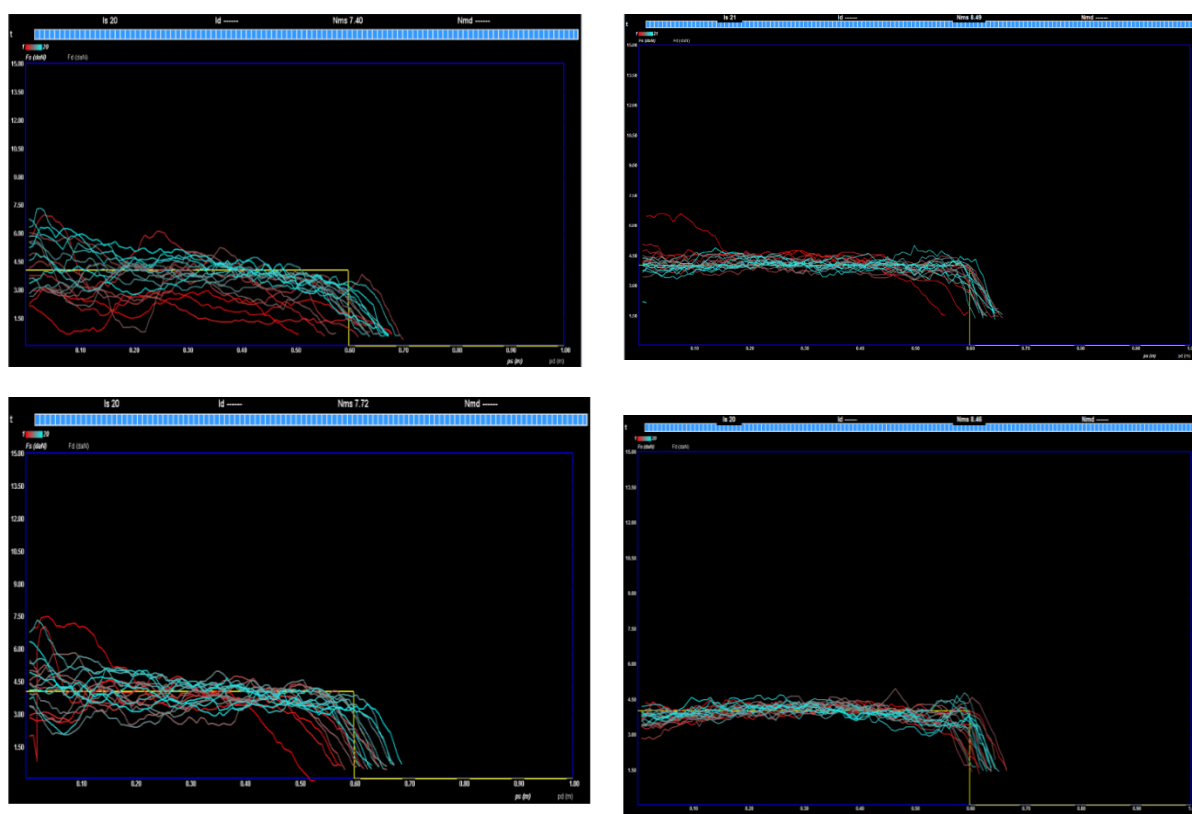


Fig. 3. The result in the initial (left) and final (right) testing for the right (up) and left (down) hands on the conditions simulator

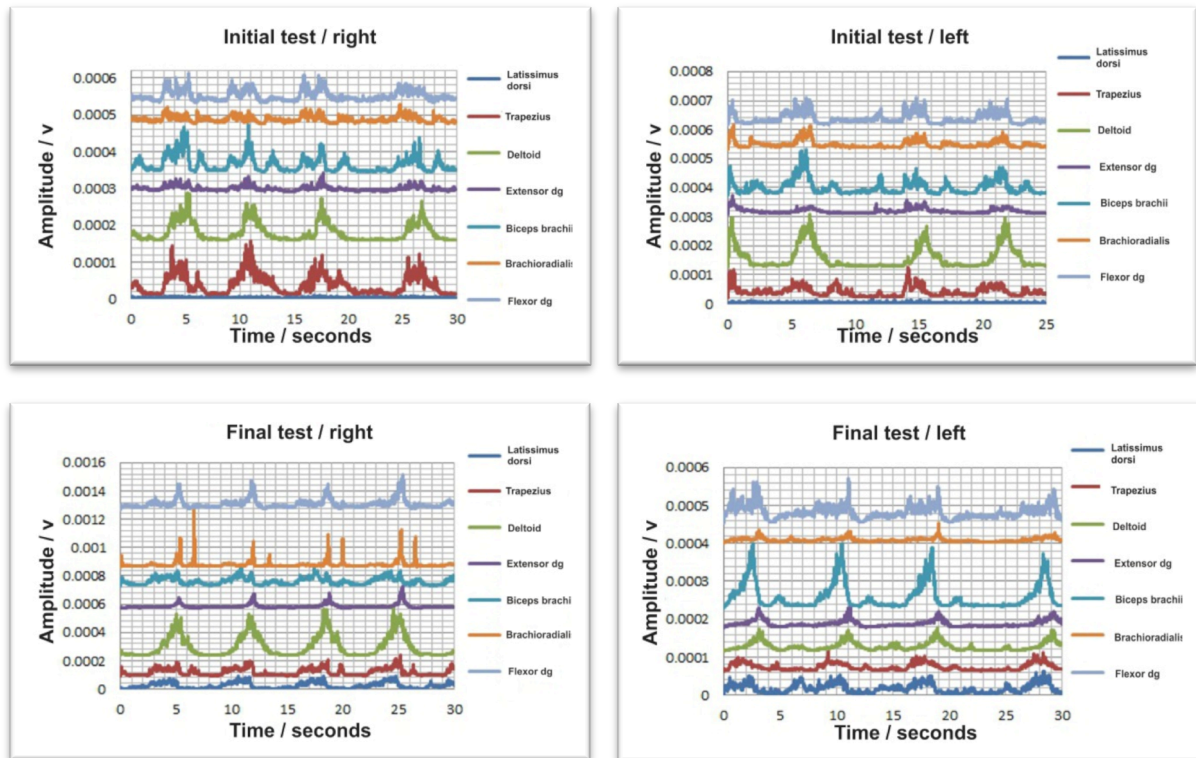


Fig. 4. The result in the initial and final testing for the left and right hands on EMG



Fig. 5. The electromyographically tested muscular groups

Concerning the muscle activity, in the initial test, the dorsal muscle did not have an important contribution to making the move. Its part of involvement was taken by the trapeze muscle, where the muscular activity was intense. This may lead to an alteration of the moves and involves the risk of premature tiredness.

In the final test, the two muscular groups start working together. Their contribution – the trapeze and dorsal muscles – to achieving the move is equal. If in the initial test the electric curves of the investigated muscular groups suggested an imprecision in movement execution, a lower control, the final test shows the benefit of the complementary control training, the muscular constriction curves revealing a controlled movement, an exquisite muscular control.

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Concerning the muscular activity, it has been shown that, in the initial test, the same problem arises on the right side – lack of participation of latissimus dorsi in executing the move, without the trapeze to take over the task. It is shown the lack of control in doing the move, too, and a weak participation of the finger extensors. The final test shows the participation of latissimus dorsi in the move, but with a slight sync mismatch.

In the final test, it is observed the benefit of the training; on the left side, the control is still poor in comparison with the right one, mainly on flexor and dorsal muscles.

The neuromuscular control of the strikes on the left side shows that the problems on the right side can be found here too. The initial test executions show the same problems with estimating the distance and execution constancy. The final test executions have been adjusted, the quality of neuromuscular executions on the non-dominant side increasing compared with the initial test on the same side.

4. Discussions and conclusions

After the experimental part of this study, we can see the following:

There has been an important increase in the quality of neuromuscular control on both the dominant and non-dominant sides.

If initially the estimation of distance and the constancy of the strike were not very good, after the training on the conditions stimulator, both of them have improved on both sides, the right and left ones.

There has been a decrease in the differences related to the quality of execution on the right and left sides. This might be due to the complementary training sessions for increasing the quality of technical execution on both the right and left arms.

After applying the complementary training program, we can see a modification in the muscular synergy through the involvement in the move of some muscular groups that have never been used before. It is about the dorsal muscle that was initially inactive and the trapeze muscle, which compensate the activity. The fact that the dorsal muscle works determines a diminution in the activity of the trapeze muscle, which leads to a more efficient strike and avoiding the onset of tiredness.

The muscular effort on the right side in the final test was more intense than on the left one. This might be a consequence of the muscle soreness.

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